# An Introduction to Kähler Manifold

#### Jacky567

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## 1 Complex manifold

**Def 1.1.** A complex manifold M is a differentiable manifold admitting an open cover  $\{U_{\alpha}\}$  and coordinate maps  $\varphi_{\alpha} : U_{\alpha} \to \mathbb{C}^n$  such that  $\varphi_{\alpha} \circ \varphi_{\beta}^{-1}$  is holomorphic on  $\varphi_{\beta}(U_{\alpha} \cap U_{\beta}) \subset \mathbb{C}^n$  for all  $\alpha, \beta$ .

**Def 1.2.** A function on an open set  $U \subset M$  is holomorphic if for all  $\alpha$ ,  $f \circ \varphi_{\alpha}^{-1}$  is holomorphic on  $\varphi_{\alpha}(U \cap U_{\alpha}) \subset \mathbb{C}^{n}$ .

 $z = (z_1, \dots, z_n)$  of functions on  $U \subset M$  is said to be a holomorphic coordinate system if  $\varphi_{\alpha} \circ z^{-1}$  and  $z \circ \varphi_{\alpha}^{-1}$  are holomorphic on  $z(U \cap U_{\alpha}), \varphi_{\alpha}(U \cap U_{\alpha})$  resp.

A map  $f: M \to N$  of complex manifolds is holomorphic if it is given in terms of local holomorphic coordinates on N by holomorphic functions.

Exam 1.1. One-dimensional complex manifold is called a Riemann surface

 $\mathbb{P}^n = \{ \text{lines through the origin in } \mathbb{C}^{n+1} \}$  is the complex projective space, with homogeneous coordinates  $z = [z_0 : \cdots : z_n].$ 

 $\mathbb{C}^n/\Lambda$  is the complex torus, where  $\Lambda = \mathbb{Z}^k \subset \mathbb{C}^k$  is a discrete lattice.

**Def 1.3.**  $T_{\mathbb{R},p}(M)$  is the real tangent space to M at p, it can be realized as the space of  $\mathbb{R}$ linear derivations on the ring of real-valued  $C^{\infty}$  functions in a neighborhood of p. If we write  $z_j = x_j + iy_j$ , then

$$T_{\mathbb{R},p}(M) = \mathbb{R}\left\{\frac{\partial}{\partial x_i}, \frac{\partial}{\partial y_i}\right\}$$

 $T_{\mathbb{C},p}(M) = T_{\mathbb{R},p}(M) \otimes_{\mathbb{R}} \mathbb{C}$  is called the complexified tangent space to M at p, it can be realized as the space of  $\mathbb{C}$ -linear derivations on the ring of complex-valued  $C^{\infty}$  functions in a neighborhood of p. We can write

$$T_{\mathbb{C},p}(M) = \mathbb{C}\left\{\frac{\partial}{\partial x_j}, \frac{\partial}{\partial y_j}\right\} = \mathbb{C}\left\{\frac{\partial}{\partial z_j}, \frac{\partial}{\partial \bar{z}_j}\right\}$$

where

$$\frac{\partial}{\partial z_j} = \frac{1}{2} \left( \frac{\partial}{\partial x_j} - i \frac{\partial}{\partial y_j} \right), \frac{\partial}{\partial \bar{z}_j} = \frac{1}{2} \left( \frac{\partial}{\partial x_j} + i \frac{\partial}{\partial y_j} \right)$$

 $T'_p(M) = \mathbb{C}\left\{\frac{\partial 1}{\partial z_j}\right\}$  is called the holomorphic tangent space, it can be realized as the subspace of  $T_{\mathbb{C},p}(M)$  consisting of derivations that vanish on antiholomorphic functions. And it is independent of the holomorphic coordinate system chosen.

The subspace  $T_p''(M) = \mathbb{C}\left\{\frac{\partial}{\partial \bar{z}_j}\right\}$  is called the antiholomorphic tangent space, and we have

$$T_{\mathbb{C},p}(M) = T'_p(M) \oplus T''_p(M).$$

**Prop 1.1.** A map  $f: M \to N$  is holomorphic iff

$$f_*(T'_p(M)) \subset T'_{f(p)}(N)$$

for all  $p \in M$ .

**Prop 1.2.**  $T''_p(M) = \overline{T'_p(M)}$  with operation of conjugation  $\frac{\partial}{\partial z_j} \mapsto \frac{\partial}{\partial \overline{z_j}}$ .  $T_{\mathbb{R},p}(M) \to T_{\mathbb{C},p}(M) \to T'_p(M)$  is an isomorphism

**Exam 1.2.** For a smooth curve z(t) = x(t) + iy(t) in  $\mathbb{C}$ , the tangent to the are can be taken either as

$$x'(t)\frac{\partial}{\partial x} + y'(t)\frac{\partial}{\partial y} \in T_{\mathbb{R}}(\mathbb{C})$$

or

$$z'(t)\frac{\partial}{\partial z} \in T'(\mathbb{C})$$

Remark 1.1. Let  $(z_1, \dots, z_n), (w_1, \dots, w_m)$  be the holomorphic coordinates centered at  $p \in M, q \in N$  resp. and  $f: M \to N$  is a holomorphic map with f(p) = q.

If we write  $z_j = x_j + iy_j, w_\alpha = u_\alpha + iv_\alpha$ , then  $f_*: T_{\mathbb{R},p}(M) \to T_{\mathbb{R},q}(N)$  is given by

$$J_{\mathbb{R}}(f) = \left[ \begin{array}{c|c} \frac{\partial u_{\alpha}}{\partial x_{j}} & \frac{\partial u_{\alpha}}{\partial y_{j}} \\ \hline \frac{\partial v_{\alpha}}{\partial x_{j}} & \frac{\partial v_{\alpha}}{\partial y_{j}} \end{array} \right]$$

And  $f_*: T_{\mathbb{C},p}(M) \to T_{\mathbb{C},q}(N)$  is given by

$$J_{\mathbb{C}}(f) = \begin{bmatrix} J(f) & 0\\ 0 & \overline{J(f)} \end{bmatrix}$$

where

$$J(f) = \left(\frac{\partial w_{\alpha}}{\partial z_j}\right)$$

If m = n, then det  $J_{\mathbb{R}}(f) = |\det J(f)|^2 \ge 0$ , *i.e.* holomorphic maps are orientation preserving.

**Prop 1.3.**  $\mathbb{C}^n$  has natural orientation given by 2*n*-form

$$\left(\frac{i}{2}\right)^n (\mathrm{d}z_1 \wedge \mathrm{d}\bar{z}_1) \wedge \dots \wedge (\mathrm{d}z_n \wedge \mathrm{d}\bar{z}_n) = \mathrm{d}x_1 \wedge \mathrm{d}y_1 \wedge \dots \wedge \mathrm{d}y_n$$

Moreover, any complex manifold has natural orientation.

## 2 Submanifolds and subvarieties

**Thm 2.1** (Implicit Function Theorem). Given holomorphic functions  $f_1, \dots, f_k : U \to \mathbb{C}$  with a neighborhood U of 0 such that

$$\det\left(\frac{\partial f_i}{\partial z_j}\right) = 0$$

Then there exists functions  $w_1, \dots, w_k$  defined in a neighborhood of  $0 \in \mathbb{C}^{n-k}$  such that in a neighborhood of 0 in  $\mathbb{C}^n$ ,

$$f_1(z) = \cdots = f_k(z) = 0 \Leftrightarrow z_i = w_i(z_{k+1}, \cdots, z_n).$$

**Def 2.1.** A complex submanifold S of a complex manifold M is a subset  $S \subset M$  given locally either as the zeros of a collection  $f_1, \dots, f_k$  of holomorphic functions with rank J(f) = k, or as the image of an open set U in  $\mathbb{C}^{n-k}$  under a map  $f: U \to M$  with rank J(f) = n - k.

Remark 2.1. By the implicit function theorem, two conditions are equivalent, and S has naturally the structure of a complex manifold of dimension n - k.

**Def 2.2.** An analytic subvariety V of a complex manifold is a subset given locally as the zeros of a finite collection of holomorphic functions.

A point  $p \in V$  is called a smooth point of V if V is a submanifold of M near p, and the locus of smooth points of V is denoted by  $V^*$ , a point  $p \in V - V^*$  is called a singular point of V,  $V_s = V - V^*$  is called the singular locus.

V is called smooth or nonsingular if  $V = V^*$ .

**Prop 2.1.** smooth analytic subvariety V is a submanifold of M.

**Def 2.3.** An analytic variety V is called irreducible, if there does not exists proper subvariety  $V_1, V_2$  of V such that  $V_1 \cup V_2 = V$ .

**Prop 2.2.** An analytic variety V is irreducible iff  $V^*$  is connected.

Proof.  $\Leftarrow$ : Suppose  $V = V_1 \cup V_2$ . Then  $V_1 \cap V_2 \subset V_s$ , *i.e.*  $V^*$  is disconnected, contradiction!

# 3 Calculus on Complex Manifolds

**Def 3.1.** For p + q = n, define  $\Omega^{p,q} = \{\varphi \in \Omega^n | \varphi(z) \in \bigwedge^p (T'_z)^*(M) \otimes \bigwedge^q (T''_z)^*(M)\}$ , the form in  $\Omega^{p,q}$  is said to be of type (p,q).

**Prop 3.1.** For  $\varphi \in \Omega^{p,q}$ ,  $d\varphi \in \Omega^{p+1,q} \oplus \Omega^{p,q+1}$ .

**Def 3.2.**  $\partial = \pi^{p+1,q} \circ d : \Omega^{p,q} \to \Omega^{p+1,q}, \bar{\partial} = \pi^{p,q+1} \circ d : \Omega^{p,q} \to \Omega^{p,q+1}$  and then  $d = \partial + \bar{\partial}$ .

**Prop 3.2.** For  $\varphi = \varphi_{IJ}(z) dz^I \wedge d\bar{z}^J$  with |I| = p, |J| = q, the operators  $\partial$  and  $\bar{\partial}$  is given by

$$\partial \varphi = \frac{\partial}{\partial z^i} \varphi_{IJ}(z) dz^i \wedge dz^I \wedge d\bar{z}^J$$
$$\bar{\partial} \varphi = \frac{\partial}{\partial \bar{z}^j} \varphi_{IJ}(z) d\bar{z}^j \wedge dz^I \wedge d\bar{z}^J$$

**Def 3.3.** A hermitian metric on M is given by a positive definite hermitian inner product

$$(\bullet, \bullet)_z : T'_z(M) \otimes \overline{T'_z(M)} \to \mathbb{C}$$

on the holomorphic tangent space at z for each  $z \in M$ , depending smoothly on z, that is, such that for local coordinates z on M, the functions  $h_{ij}(z) = \left(\frac{\partial}{\partial z_i}, \frac{\partial}{\partial z_j}\right)_z$  are smooth.

*Remark* 3.1. Writing  $(\bullet, \bullet)_z$  in terms of the basis  $\{ dz_i \otimes d\bar{z}_j \}$  for  $\left( T'_z(M) \otimes \overline{T'_z(M)} \right)^*$ , the hermitian matrix is given by

$$\mathrm{d}s^2 = \sum_{i,j} h_{ij}(z) \mathrm{d}z_i \otimes \mathrm{d}\bar{z}_j$$

**Def 3.4.** A coframe for the hermitian metric is an *n*-tuple of forms  $(\varphi_1, \dots, \varphi_n)$  of type (1, 0) such that

$$\mathrm{d}s^2 = \sum_i \varphi_i \otimes \bar{\varphi}_i,$$

*i.e.*  $(\varphi_1(z), \cdots, \varphi_n(z))$  is an orthonormal basis for  $(T'_z)^*(M)$ .

**Def 3.5.** By the  $\mathbb{R}$  linear isomorphism  $T_{\mathbb{R},z}(M) \to T'_z(M)$ ,

$$\mathbb{R}ds^2: T_{\mathbb{R},z}(M) \otimes T_{\mathbb{R},z}(M) \to \mathbb{R}$$

is a Riemannian metric and the quadratic form

$$\operatorname{Im} \mathrm{d} s^2 : T_{\mathbb{R},z}(M) \otimes T_{\mathbb{R},z}(M) \to \mathbb{R}$$

is alternating, *i.e.* it represents a real differential form of degree 2.  $\omega = -\frac{1}{2} \operatorname{Im} ds^2$  is called the associated (1, 1)-form of the metric.

**Prop 3.3.**  $\omega = \frac{i}{2} \sum \varphi_j \wedge \bar{\varphi}_j$ 

*Proof.* Let  $\varphi_j = \alpha_j + i\beta_j$ .

Then

$$\mathrm{d}s^2 = \sum (\alpha_j \otimes \alpha_j + \beta_j \otimes \beta_j + i \sum (-\alpha_j \otimes \beta_j + \beta_j \otimes \alpha_j).$$

 $\operatorname{So}$ 

$$\omega = -\frac{1}{2} \operatorname{Im} \mathrm{d}s^2 = \sum \alpha_j \wedge \beta_j = \frac{i}{2} \sum \varphi_j \wedge \bar{\varphi}_j.$$

**Def 3.6.** A real differential form  $\omega$  of type (1,1) is positive if  $i\langle \omega(z), v \wedge \bar{v} \rangle > 0$  for any  $v \in T'_z(M)$ .

**Prop 3.4.** Let  $z = (z_1, \dots, z_n)$  be a local holomorphic coordinate on M, a form  $\omega$  is positive if

$$\omega(z) = \frac{i}{2} \sum h_{jk}(z) \mathrm{d}z_j \wedge \mathrm{d}\bar{z}_k$$

with  $H(z) = (h_{ij}(z))$  a positive definite hermitian matrix for each z.

**Exam 3.1.** Let  $z_0, \dots, z_n$  be the coordinates on  $\mathbb{C}^{n+1}$ , and let  $\pi : \mathbb{C}^{n+1} \setminus \{0\} \to \mathbb{P}^n$  be the standard projection map.

Let  $U \subset \mathbb{P}^n$  be an open set and  $Z: U \to \mathbb{C}^{n+1} \setminus \{0\}$  be a lifting of U, i.e.  $\pi \circ Z = \text{Id.}$ Consider the differential form  $\omega = \frac{i}{2\pi} \partial \bar{\partial} \log \|Z\|^2$ .

We claim that  $\omega$  is well-defined and positive.

For another lifting  $Z': U \to \mathbb{C}^{n+1} \setminus \{0\}$ , where f is holomorphic, let Z' = fZ, then

$$\frac{i}{2\pi}\partial\bar{\partial}\log\left\|Z'\right\|^2 = \frac{i}{2\pi}\partial\bar{\partial}\left(\log\|Z\|^2 + \log f + \log \bar{f}\right) = \omega + \frac{i}{2\pi}\left(\partial\bar{\partial}\log f - \bar{\partial}\partial\log\bar{f}\right) = \omega$$

In open set  $U_0 = \{z_0 \neq 0\}$ , consider coordinate  $w_i = \frac{z_i}{z_0}$  and lifting  $Z = (1, w_1, \cdots, w_n)$ 

$$\omega = \frac{i}{2\pi} \partial \bar{\partial} \log \left( 1 + \sum \omega_i \bar{\omega}_i \right) = \frac{i}{2\pi} \partial \left( \frac{\sum w_i \mathrm{d}\bar{w}_i}{1 + \sum w_i \bar{w}_i} \right)$$
$$= \frac{i}{2\pi} \left( \frac{\sum \mathrm{d}w_i \wedge \mathrm{d}\bar{w}_i}{1 + w_i \bar{w}_i} - \sum \frac{\left(\sum \bar{w}_i \mathrm{d}w_i\right) \wedge \left(\sum w_i \mathrm{d}\bar{w}_i\right)}{\left(1 + \sum w_i \bar{w}_i\right)^2} \right)$$

At point  $[1:0:\cdots:0]$ ,  $\omega = \frac{i}{2\pi} \sum dw_i \wedge d\bar{w}_i > 0$ . So  $\omega$  defines a Hermitain metric on  $\mathbb{P}^n$ , called the Fubini-Study metric.

## 4 Holomorphic Vector Bundles

**Def 4.1.** A holomorphic vector bundle  $E \xrightarrow{\pi} M$  is a complex vector bundle together with the structure of a complex manifold on E, *i.e.* the trivialization  $\varphi_U : E_U \to U \times \mathbb{C}^k$  is biholomorphic. (or equivalently, it has holomorphic transition function  $g_{\alpha\beta} : U_{\alpha} \cap U_{\beta} \to \mathrm{GL}_k(\mathbb{C})$ )

**Prop 4.1.** dual, direct sum, tensor, alternating product of holomorphic vector bundles are holomorphic.

**Def 4.2.** Take a local holomorphic frame  $\{e^1, \dots, e^k\}$  of E over U, define

$$\bar{\partial}: \Omega^{p,q}(E) \to \Omega^{p,q+1}(E), \omega_i \otimes e^i \mapsto \bar{\partial}\omega_i \otimes e^i.$$

**Prop 4.2.**  $\bar{\partial}$  is well-defined.

*Proof.* For another holomorphic frame  $\{(e')^1, \cdots, (e')^k\}$  of E over U, let  $e^i = g^i_j(e')^j$ . Then  $\sigma = g^i_j \omega_i \otimes (e')^j$ .

So

$$\bar{\partial}\sigma = \bar{\partial}(g_{ij}\omega^i) \otimes (e')^j = g_j^i \cdot \partial\omega_i \otimes (e')^j = \bar{\partial}\omega_i \otimes e^i$$

since  $g_{ij}$  is holomorphic.

**Exam 4.1.** T'(M) is called holomorphic tangent bundle.

#### 5 Metrics, connections and curvature

**Def 5.1.** A hermitian metric on E is a hermitian inner product on each fiber  $E_x$  of E varying smoothly with  $x \in M$ , *i.e.* for a frame  $\zeta = \{\zeta_1, \dots, \zeta_k\}$  of E,  $h_{ij}(x) = (\zeta_i(x), \zeta_j(x))$  is smooth.

The frame  $\zeta$  is called unitary if  $\zeta_1(x), \dots, \zeta_k(x)$  is orthonormal basis for  $E_x$ . A holomorphic vector bundle with a hermitian metric is called a hermitian vector bundle.

**Def 5.2.** A connection D on  $E \to M$  is a map  $D: \Omega^0(E) \to \Omega^1(E)$  satisfying the Leibnitz rule:

$$D(f\zeta) = \mathrm{d}f \otimes \zeta + f \cdot D(\zeta)$$

for all sections  $\zeta \in \Omega^0(E)(U), f \in C^{\infty}(U)$ .

Let  $e = \{e^1, \dots, e^n\}$  be a frame for E over U, write  $De^i = \theta^i_j e^j$ , where  $\theta = (\theta_{ij})$  is a matrix of 1-forms, called the connection matrix of D w.r.t. e.

Remark 5.1. For general  $\sigma = \sigma_i e^i$ , we have

$$D\sigma = \mathrm{d}\sigma_i \cdot e^i + \sigma_i \cdot De^i = \left(\mathrm{d}\sigma_j + \sigma_i\theta_i^i\right)e^j$$

For another frame  $e' = \{(e')^1, \cdots, (e')^n\}$  with  $(e')^i = \sum g_j^i e^j$ , then

$$D(e')^{i} = \sum \mathrm{d}g_{j}^{i} \cdot e_{j} + \sum g_{k}^{i}\theta_{j}^{k}e^{j}$$

 $\operatorname{So}$ 

$$\theta_{e'} = \mathrm{d}g \cdot g^{-1} + g \cdot \theta_e \cdot g^{-1}.$$

**Def 5.3.** If *E* is hermitian, we say connection *D* on *E* is compatible with the complex structure if  $D'' = \bar{\partial}$ , where D = D' + D'' with  $D' : \Omega^0(E) \to \Omega^{1,0}(E), D'' : \Omega^0(E) \to \Omega^{0,1}(E)$ .

D is said to be compatible with the metric if  $d(\xi, \eta) = (D\xi, \eta) + (\xi, D\eta)$ .

**Thm 5.1.** If E is hermitian, there is a unique connection D on E compatible with both the metric and the complex structure.

*Proof.* Let  $e = \{e_1, \dots, e_n\}$  be a holomorphic frame and  $h_{ij} = (e_i, e_j)$ .

If such D exists, then  $D''e_i = \bar{\partial}e_i = 0$ .

So connection matrix  $\theta$  must have type (1,0), and

$$\mathrm{d}h_{ij} = \mathrm{d}\left(e_i, e_j\right) = \theta_i^k h_{kj} + \bar{\theta}_j^k h_{ik}$$

Therefore  $\partial h_{ij} = \theta_i^k h_{kj}$ , *i.e.* $\partial h = \theta h$  and  $\bar{\partial} h_{ij} = \bar{\theta}_j^k h_{ik}$ , *i.e.* $\bar{\partial} h = h \bar{\theta}^T$ . Hence  $\theta = \partial h \cdot h^{-1}$  is the unique solution of these two equations.

Def 5.4. This unique connection is called the associated(or metric) connection.

*Remark* 5.2. If  $e_1, \dots, e_n$  is a unitary frame, then  $\theta_i^j + \bar{\theta}_j^i = d(e_i, e_j) = 0$ , *i.e.* the connection matrix w.r.t. a unitary frame is skew-hermitian.

# 6 Kähler manifold

**Def 6.1.** A compact complex manifold M with a hermitian metric  $ds^2$  is called Kähler if its associated (1, 1)-form  $\omega$  is d-closed(Sympletic structure)

**Def 6.2.** We say a metric  $ds^2$  on M osculates to order k to the Euclidean on  $\mathbb{C}^n$  if for every point  $p \in M$ , we can find a holomorphic coordinate system (z) in a neighborhood of p for which

$$\mathrm{d}s^2 = \sum (\delta_{ij} + g_{ij}) \mathrm{d}z^i \otimes \mathrm{d}\bar{z}^j$$

where  $g_{ij}$  vanishes up to order k at p, written as

$$\mathrm{d}s^2 = \sum (\delta_{ij} + [k]) \mathrm{d}z^i \otimes \mathrm{d}\bar{z}^j$$

**Prop 6.1.**  $ds^2$  is Kähler iff it osculates to order 2 to the Euclidean metric everywhere.

- $\begin{array}{l} \textit{Proof.} \ \Leftarrow \ \text{is trivial.} \\ \Rightarrow: \ \text{Let} \ \omega = \frac{i}{2} \sum_{j \in \overline{l}} (\delta_{jk} + a_{jkl} z^l + a_{jk\overline{l}} \overline{z}_l + [2]) \mathrm{d} z_j \wedge \mathrm{d} \overline{z}_k \\ \text{Then} \ a_{jk\overline{l}} = \overline{a_{jkl}} \ \text{and} \ a_{jkl} = a_{lkj} \ \text{since} \ \mathrm{d} \omega = 0. \\ \text{Let} \ z^l = w^l + \frac{1}{2} \sum_{j \in \overline{l}} b_{mn}^l w^m w^n \ \text{with} \ b_{mn}^l = -a_{lmn}. \\ \text{We claim that} \ \omega = \frac{i}{2} \sum_{j \in \overline{l}} (\delta_{ij} + [2]) \mathrm{d} w^i \wedge \mathrm{d} \overline{w}^j. \end{array}$
- **Exam 6.1.** Any metric on a compact Riemann surface is Kähler since  $d\omega$  is 3-form. The complex torus  $T = \mathbb{C}^N / \Lambda$  is Kähler with Euclidean metric  $ds^2 = \sum dz_i \otimes d\overline{z}_i$ . If M, N are Kähler, then  $M \times N$  is Kähler with product metric. If  $S \subset M$  is a submanifold and M is Kähler, then S is Kähler with pull-back (1,1)-form  $i^*\omega$ Consider Fubini-Study metric on  $\mathbb{P}^n$ , its associated (1,1)-form is

$$\omega = \frac{\sqrt{-1}}{2\pi} \partial \bar{\partial} \log \|Z\|^2 = \frac{\sqrt{-1}}{4\pi} (\partial + \bar{\partial})(\bar{\partial} - \partial) \log \|Z\|^2 = \frac{\sqrt{-1}}{4\pi} d\left((\bar{\partial} - \partial) \log \|Z\|^2\right)$$

So  $\omega$  is closed, i.e. Fubini-Study metric is Kähler.

**Prop 6.2.** Any compact manifold that can be embedded in projective space  $\mathbb{P}^n$  is Kähler.